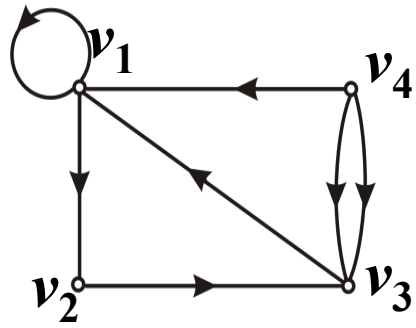


6.3.3 Adjacency Matrices of Directed and Undirected Graphs

↳ Counting Directed Paths via Adjacency Matrices

- **Theorem 6.4:** Let A be the adjacency matrix of the n -order directed graph D . Then, the elements of $A^l (l \geq 1)$:
 - $a_{ij}^{(l)}$ are the number of *paths of length l* from vertex v_i to vertex v_j in D .
 - $a_{ii}^{(l)}$ is the number of *cycles of length l* starting and ending at vertex v_i .
 - $\sum_{i=1}^n \sum_{j=1}^n a_{ij}^{(l)}$ is the *total number of paths of length l* (including cycles) in D .
 - $\sum_{i=1}^n a_{ii}^{(l)}$ is the *total number of cycles of length l* in D .

- Corollary: Let $B_l = A + A^2 + \dots + A^l$ ($l \geq 1$), Then, the elements :
- $b_{ij}^{(l)}$ are the number of paths (including cycles) of length *less than or equal to l* from vertex v_i to vertex v_j in D .
 - $b_{ii}^{(l)}$ is the number of cycles in D whose length from v_i to v_i *less than or equal to l* .
 - $\sum_{i=1}^n \sum_{j=1}^n b_{ij}^{(l)}$ is the number of paths (including cycles) in D whose length is *less than or equal to l* .
 - $\sum_{i=1}^n b_{ii}^{(l)}$ is the number of cycles in D whose length is *less than or equal to l* .



$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 2 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 3 & 1 & 0 & 0 \end{bmatrix}$$

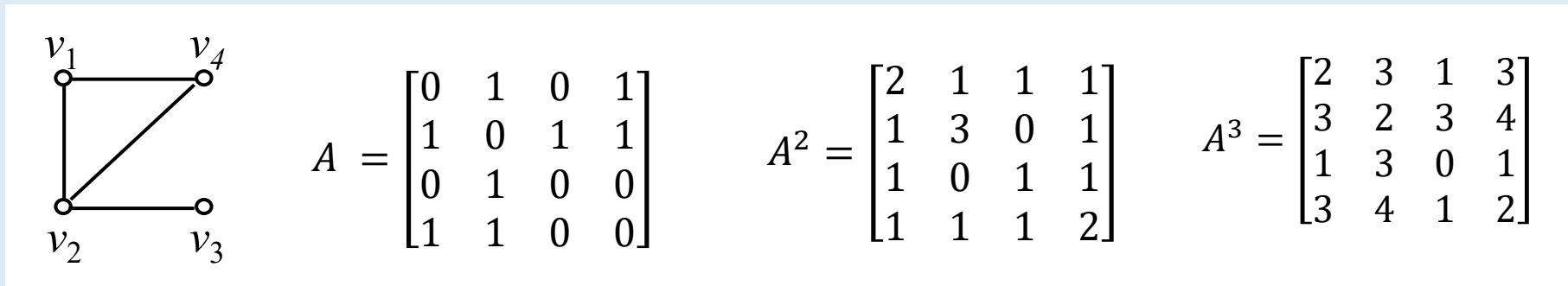
$$A^3 = \begin{bmatrix} 2 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 3 & 3 & 1 & 0 \end{bmatrix}$$

$$A^4 = \begin{bmatrix} 3 & 2 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & 0 \\ 4 & 3 & 1 & 0 \end{bmatrix}$$

- There is 1 path of length 3 from v_1 to v_2 .
- There is 1 path of length 3 from v_1 to v_3 .
- There are 2 cycles of length 3 from v_1 to itself.
- There are a total of 15 paths of length 3 in D , of which 3 are cycles.

↳ Adjacency Matrix of a Undirected Graph

- Let $G=\langle V,E\rangle$ be an undirected simple graph, where $V=\{v_1,v_2,\dots,v_n\}$.
Let $a_{ij}^{(1)}$ denote the number of edges between vertices v_i and v_j . The matrix $(a_{ij})_{n\times n}$ is called the **adjacency matrix of G** , denoted as **$A(G)$** .
- Example:** Write the adjacency matrix of an undirected graph, and find the number of paths of length 3 from v_i to v_2 and the number of cycles of length 3 from v_1 to v_1 .



There are 3 paths of length 3 from v_1 to v_2 : $v_1v_2v_1v_2$, $v_1v_2v_3v_2$, $v_1v_4v_1v_2$.
There are 2 cycles of length 3 from v_1 to v_1 : $v_1v_2v_4v_1$, $v_1v_4v_2v_1$.

↳ 6.3 Matrix Representations of Graphs

- 6.3.1 Incidence Matrix of an Undirected Graph
- 6.3.2 Incidence Matrix of a Directed Acyclic Graph
- 6.3.3 Adjacency Matrix of a Directed and Undirected Graph
The Number of Paths and Cycles in a Graph
- 6.3.4 Reachability Matrix of a Graph

↳ Reachability Matrix of Graph

- Let the graph (either undirected or directed) $G = \langle V, E \rangle$, $V = \{v_1, v_2, \dots, v_n\}$,

$$\text{let } p_{ij} = \begin{cases} 1, & v_i \text{ can reach } v_j \\ 0, & \text{otherwise} \end{cases}$$

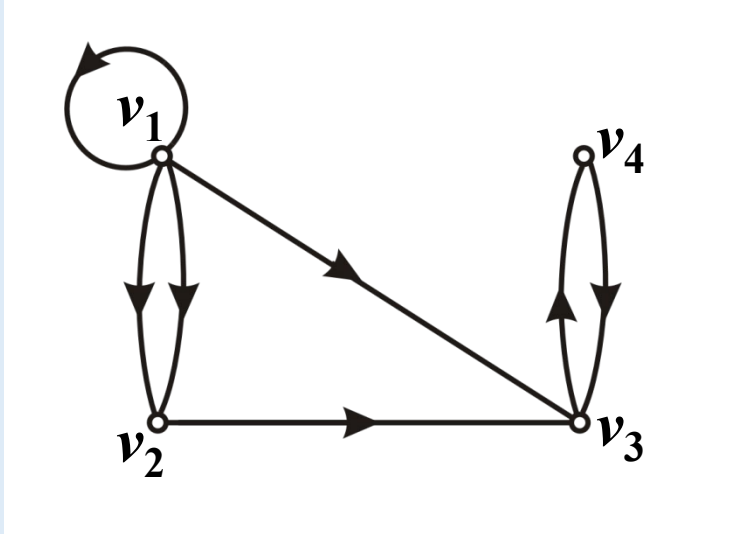
The matrix $(p_{ij})_{n \times n}$ is called the *reachability matrix* of G , denoted as $P(G)$, or simply P .

- Property:

- (1) All the elements on the *main diagonal* of $P(G)$ are 1.
- (2) The reachability matrix of an undirected graph is *symmetric*.
- (3) An *undirected graph* G is **connected** if and only if all elements of $P(G)$ are 1. A *directed graph* D is **strongly connected** if and only if all elements of $P(D)$ are 1.
- (4) For an *n-order graph*, $p_{ij}=1 \Leftrightarrow b_{ij}^{(n-1)} > 0, i \neq j$.

↳ Reachability matrix of Graph(e.g.)

■ Example:

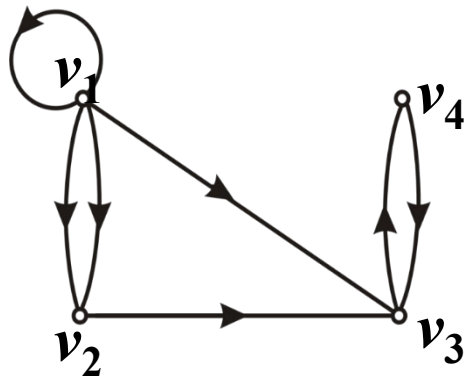


- (1) How many paths of length 3 are there from v_1 to v_4 , and from v_4 to v_1 ?
- (2) How many cycles of length 1, 2, 3, and 4 are there from v_1 to itself?
- (3) How many paths of length 4 are there in total? How many of them are cycles?
- (4) How many cycles of length less than or equal to 4 are there in total?
- (5) Write the reachability matrix of D , and is D strongly connected?

■ Solution ?

↳ Reachability matrix of Graph(e.g.)

■ Solution:



$$A = \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad A^2 = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$A^3 = \begin{bmatrix} 1 & 2 & 4 & 3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad A^4 = \begin{bmatrix} 1 & 2 & 6 & 4 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad P = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

- (1) There are 3 paths of length 3 from v_1 to v_4 . There are 0 paths of length 3 from v_4 to v_1 .
- (2) There are 1 cycles of length 1, 2, 3, and 4 from v_1 to itself.
- (3) There are 16 paths of length 4, of which 3 are cycles.
- (4) There are 8 cycles of length less than or equal to 4.

(5) Reachability Matrix: $P(G)$

6.3 Matrix Representations of Graphs • Brief summary

Objective :

Key Concepts :



Discrete Mathematics 2025 Spring



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- 6.1 Basic Concepts of Graphs
- 6.2 Connectivity of Graphs
- 6.3 Matrix Representations of Graphs
- 6.4 Several Special Types of Graphs

■ 6.4.1 Bipartite Graphs

Necessary and sufficient conditions for a graph to be bipartite
matching, maximal matching, maximum matching, complete matching, perfect matching

■ 6.4.2 Eulerian Graphs

Eulerian circuits (paths) and their necessary and sufficient conditions for existence

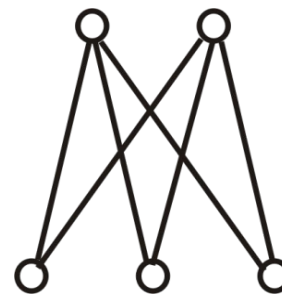
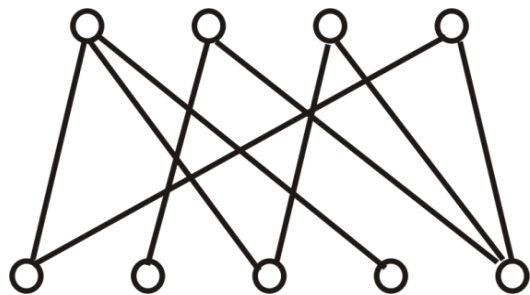
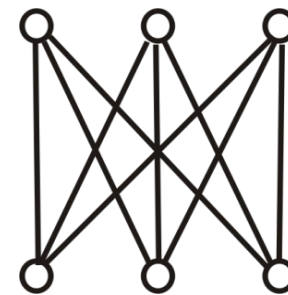
■ 6.4.3 Hamiltonian Graphs

Hamiltonian circuits (paths) and the necessary and sufficient conditions for their existence

■ 6.4.4 Planar Graphs

↳ Bipartite Graph and Complete Bipartite Graph

- Let $G=\langle V,E\rangle$ be an undirected graph. If it is possible to partition V into two sets V_1 and V_2 such that: $V_1\cup V_2=V$, $V_1\cap V_2=\emptyset$, Each edge in G has one endpoint in V_1 and the other in V_2 , then G is called a **bipartite graph**, denoted as $\langle V_1, V_2, E \rangle$, and V_1 and V_2 are called **complementary vertex subsets**.
- Furthermore, if G is a simple graph and every vertex in V_1 is adjacent to every vertex in V_2 , then G is called a **complete bipartite graph**, denoted as $K_{r,s}$, where $r=|V_1|$ and $s=|V_2|$.

 $K_{2,3}$  $K_{3,3}$

↳ Cycle Characterization of Bipartite Graphs

■ **Theorem 6.5:** An undirected graph $G=\langle V,E \rangle$ is a bipartite graph if and only if it contains no odd-length cycles.

■ **Proof:**

(1) **Necessity:** Let $G=\langle V_1, V_2, E \rangle$ be a bipartite graph. Each edge can only connect V_1 to V_2 or V_2 to V_1 , so any cycle in G must have even length.

(2) **Sufficiency:** Assume G has at least one edge and is connected.

Take any vertex u , and define:

$V_1 = \{v \mid v \in V \text{ and the distance from } v \text{ to } u \text{ is even}\}$

$V_2 = \{v \mid v \in V \text{ and the distance from } v \text{ to } u \text{ is odd}\}$

Then, $V_1 \cup V_2 = V$, $V_1 \cap V_2 = \emptyset$.

■ Proof:

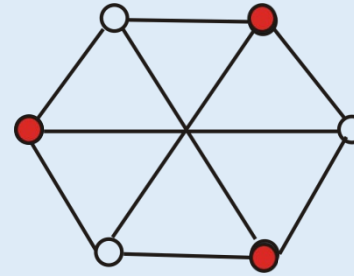
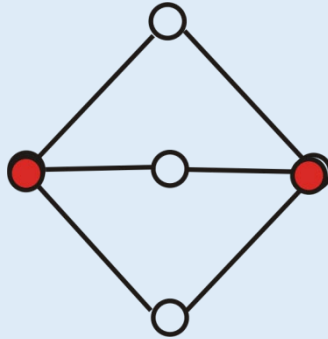
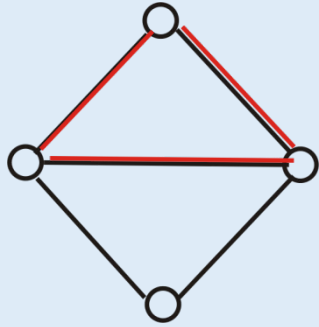
(2) **Sufficiency:** Assume G has at least one edge and is connected. Take any vertex u , and define:

$V_1 = \{v \mid v \in V \text{ and the distance from } v \text{ to } u \text{ is even}\}$

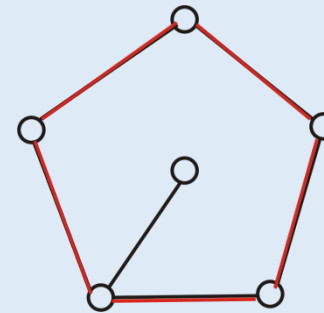
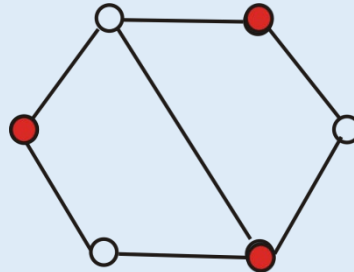
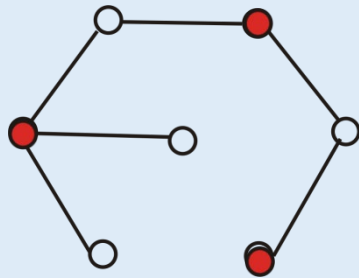
$V_2 = \{v \mid v \in V \text{ and the distance from } v \text{ to } u \text{ is odd}\}$

Then, $V_1 \cup V_2 = V$, $V_1 \cap V_2 = \emptyset$.

- First, we prove that no two vertices in V_1 are adjacent. Suppose there exist $s, t \in V_1$ such that $e = (s, t) \in E$. Let Γ_1 and Γ_2 be the shortest paths from u to s and u to t , respectively. Then, $\Gamma_1 \cup e \cup \Gamma_2$ forms a cycle of odd length, which contradicts the assumption.
- Similarly, we can prove that no two vertices in V_2 are adjacent.



Non-bipartite graph



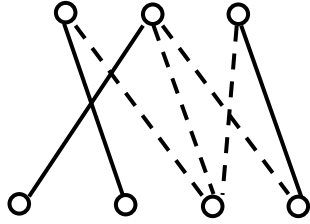
Non-bipartite graph

↳ Matchings and Complete Matchings in Bipartite Graphs

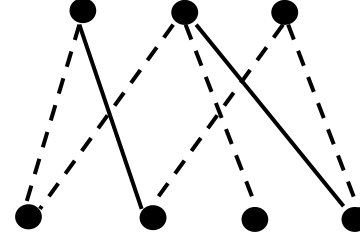
- **Definition 6.11:** Let $G = \langle V_1, V_2, E \rangle$ be a bipartite graph, where $E' \subseteq E$. If the edges in E' are pairwise non-adjacent, then E' is called a **matching** in G . If adding any edge to E' results in a set of edges that is no longer a matching, then E' is called a **maximal matching** in G . The matching in G with the maximum number of edges is called the **maximum matching** of G .
- Moreover, suppose $|V_1| \leq |V_2|$ and E' is a matching in G . If $|E'| = |V_1|$, then E' is called a **complete matching** from V_1 to V_2 .
- When $|V_1| = |V_2|$, a complete matching is called a **perfect matching**.

6.4.1 Bipartite Graphs

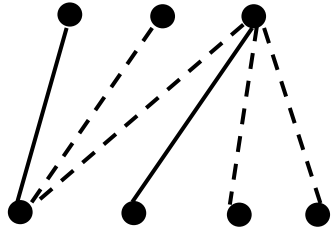
↳ Matchings and Complete Matchings in Bipartite Graphs(e.g.)



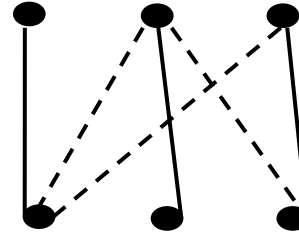
Maximum Matching and
Complete Matching



Maximal Matching



Maximum Matching



Perfect Matching

↳ Complete Matching Existence Theorem

■ Theorem 6.6 (Hall's Theorem):

Let $G = \langle V_1, V_2, E \rangle$ be a bipartite graph with $|V_1| = |V_2|$.

There *exists a complete matching* from V_1 to V_2 in G if and only if, for any k (where $1 \leq k \leq |V_1|$), the set of k vertices in V_1 is adjacent to at least k vertices in V_2 (the *distinctness condition*).

■ Theorem 6.7:

Let $G = \langle V_1, V_2, E \rangle$ be a bipartite graph with $|V_1| \leq |V_2|$. If there exists a positive integer t such that each vertex in V_1 is connected to at least t edges, and each vertex in V_2 is connected to at most t edges (the *t-condition*), then there *exists a complete matching* from V_1 to V_2 in G .

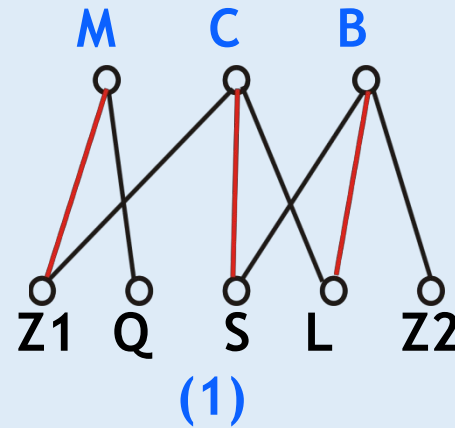
↳ Application Examples of Complete Matchings

■ Example:

A middle school has three extracurricular activity groups: the Math Group, the Computer Group, and the Biology Group. There are five students: Zhao, Qian, Sun, Li, and Zhou. In each of the following three cases, determine whether it is possible to select three students to serve as group leaders, one for each group:

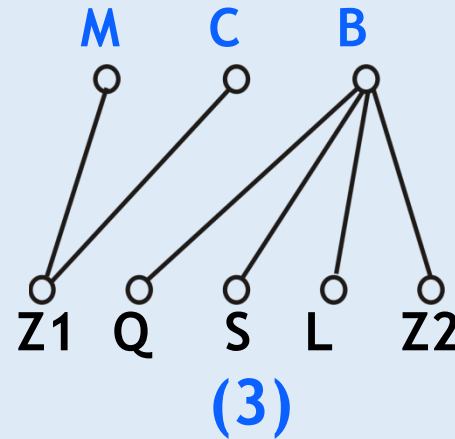
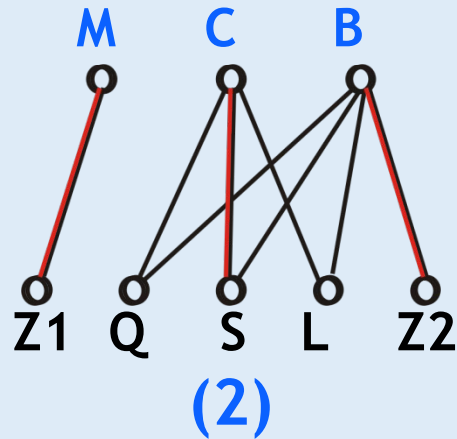
- (1) Zhao and Qian are members of the Math Group; Zhao, Sun, and Li are members of the Computer Group; Sun, Li, and Zhou are members of the Biology Group.
- (2) Zhao is a member of the Math Group; Qian, Sun, and Li are members of the Computer Group; Qian, Sun, Li, and Zhou are members of the Biology Group.
- (3) Zhao is a member of both the Math and Computer Groups; Qian, Sun, Li, and Zhou are members of the Biology Group.

M: Math Group
C: Computer Group
B: Biology Group
Z1: Zhao
Q: Qian
S: Sun
L: Li
Z2: Zhou



A complete matching corresponds to a feasible assignment.

(1) and (2) admit complete matchings, with multiple possible assignments.



(3) does not satisfy the distinctness condition, so no complete matching exists.