



Discrete Mathematics 2025 Spring



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- 6.1 Basic Concepts of Graphs
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■ 6.2.1 Paths and Circuits

Elementary Paths (Circuits) and Simple Paths (Circuits)

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Vertex Connectivity and Edge Connectivity

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Reachability

Weak Connectivity, Unilateral Connectivity, and Strong Connectivity

Shortest Paths and Distances

↳ Elementary Paths (Circuits) and Simple Paths (Circuits)

- **Definition 6.8:** Given a graph $G = \langle V, E \rangle$ (either undirected or directed), an alternating sequence of vertices and edges in G $\Gamma = v_0 e_1 v_1 e_2 \dots e_l v_l$.
- (1) $\forall i (1 \leq i \leq l)$, $e_i = (v_{i-1}, v_i)$. Γ is called a **path** from v_0 to v_l , v_0 and v_l are called the **starting point** and **ending point** of the path, respectively, and l is the **length** of the path. If $v_0 = v_l$, Γ the path is called a **circuit** (or **cycle**).
- (2) If all the vertices in a path or circuit are distinct (except for $v_0 = v_l$ in the case of a circuit), it is called an **elementary path** or **simple path** (and an **elementary circuit** or **simple cycle**). A cycle of odd length is called an **odd cycle**, and a cycle of even length is called an **even cycle**.
- (3) If all edges in a path or circuit are distinct, it is called a **simple path** (or **simple circuit**); otherwise, it is called a **non-simple** or **complex path** (or **complex circuit**).

↳ Representations of a Path or Circuit

■ Representations of a Path or Circuit

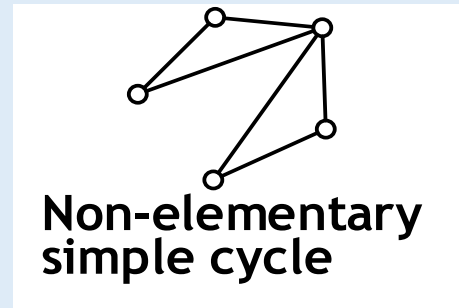
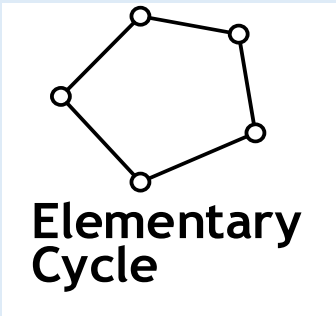
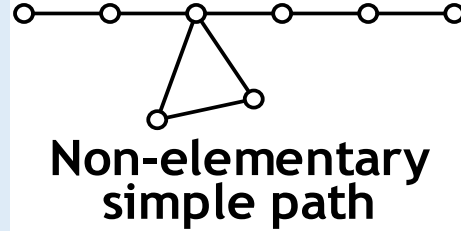
- ① According to the definition, using an *alternating sequence* of vertices and edges: $\Gamma = v_0 e_1 v_1 e_2 \dots e_l v_l$.
- ② Using a *sequence of edges*: $\Gamma = e_1 e_2 \dots e_l$.
- ③ In a simple graph, using a *sequence of vertices*: $\Gamma = v_0 v_1 \dots v_l$

■ Properties of Circuits

- In an undirected graph, a *circuit of length 1* is formed by a *loop* (an edge connecting a vertex to itself). A *circuit of length 2* is formed by *two parallel edges* between the same pair of vertices. In an undirected simple graph, all *circuits have length ≥ 3* .
- In a directed graph, a circuit of length 1 is also formed by a loop. In a directed simple graph, all circuits have length ≥ 2 .

↳ Elementary paths (or circuit) $\subset$ simple paths (or circuit)

- Every elementary path (or circuit) is a simple path (or circuit), but the converse is not necessarily true.
- **Example:**



■ 6.2.1 Paths and Circuits

Elementary Paths (Circuits) and Simple Paths (Circuits)

■ 6.2.2 Connectivity and Connectedness in Undirected Graphs

Connected Graphs and Connected Components

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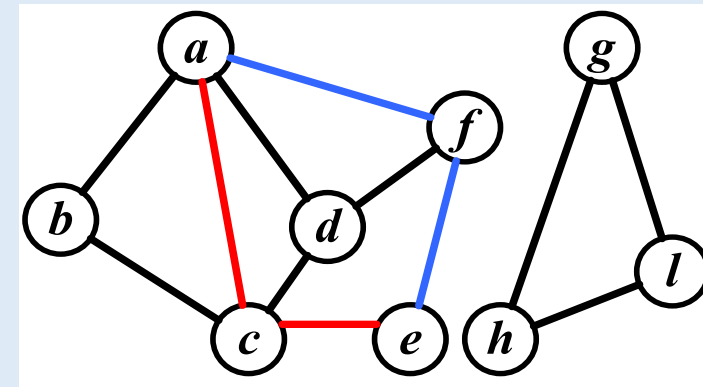
- Let $G=\langle V,E\rangle$ be an undirected graph, and let $u,v\in V$
 - **Connectivity between u and v** : Vertex u is said to be **connected** to vertex v if there exists a path between them. By convention, every vertex is considered to be connected to itself.
 - **Connected graph**: A graph in which every pair of vertices is connected. A trivial graph (with only one vertex) is considered connected.
 - **Connectivity relation**: $R=\{\langle u,v\rangle \mid u,v \in V \text{ and } u \text{ is connected to } v\}$. R is an equivalence relation.
 - **Connected component**: The subgraph induced by each equivalence class of V under the relation R is called a **connected component** of G . Suppose $V/R=\{V_1,V_2,\dots,V_k\}$, then the connected components of G are the subgraphs $G[V_1],G[V_2],\dots,G[V_k]$.
 - **Number of connected components**: $p(G)=k$
 G is a connected graph $\Leftrightarrow p(G)=1$.

6.2.2 Connectivity and Connectedness in Undirected

↳ Shortest Paths and Distances in Undirected Graphs

- **Shortest path between u and v :** A path of the shortest length between vertices u and v , assuming u and v are connected.
- **Distance between u and v $d(u,v)$:** The length of the shortest path between u and v . If u and v are not connected, define $d(u,v)=\infty$.
- **Property:**

- (1) $d(u,v) \geq 0$, and $d(u,v)=0 \Leftrightarrow u=v$
- (2) $d(u,v)=d(v,u)$
- (3) $d(u,v)+d(v,w) \geq d(u,w)$



- **For example:** The shortest path between a and e is shown in the figure on the right: ace , afe . $d(a,e)=2$, $d(a,h)=\infty$

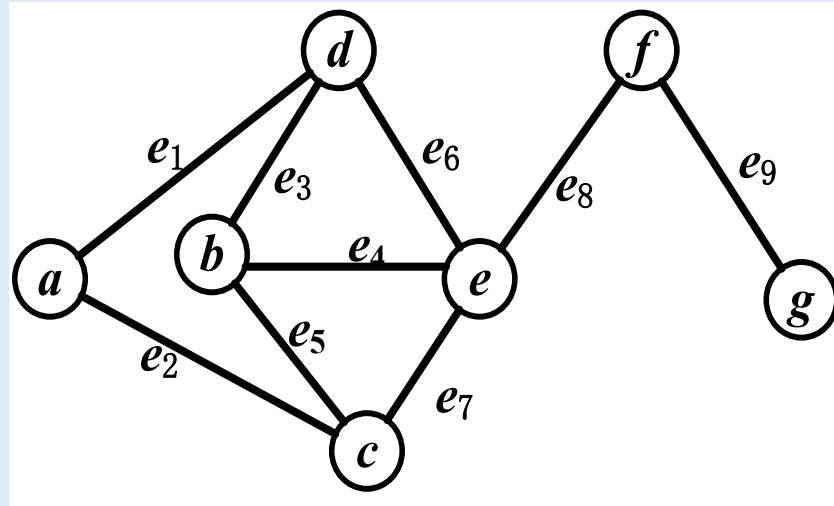
6.2.2 Connectivity and Connectedness in Undirected

↳ Vertex Cuts and Edge Cuts in Undirected Graphs

- Let undirected graph $G = \langle V, E \rangle$, $v \in V$, $e \in E$, $V' \subseteq V$, $E' \subseteq E$.
 - $G - v$: The graph obtained by removing vertex v and all edges incident to it from G .
 - $G - V'$: The graph obtained by removing all vertices in V' and their incident edges from G .
 - $G - e$: The graph obtained by removing edge e from G .
 - $G - E'$: The graph obtained by removing all edges in E' from G .
- **Definition 6.9:** Let undirected graph $G = \langle V, E \rangle$, $V' \subset V$, If $p(G - V') > p(G)$, then V' is called a **vertex cut set** of G . if $\{v\}$ is vertex cut set, then v is called a **cut vertex**.
 - Let $E' \subseteq E$, if $p(G - E') > p(G)$, then E' is called an **edge cut set** of G . If $\{e\}$ is edge cut set, then e is called a **cut edge** or a **bridge**.

6.2.2 Connectivity and Connectedness in Undirected

↳ Vertex Cuts and Edge Cuts in Undirected Graphs(e.g.)



Cut vertex: e, f

Vertex cut set : $\{e\}, \{f\}, \{c, d\}$

Bridge: e_8, e_9

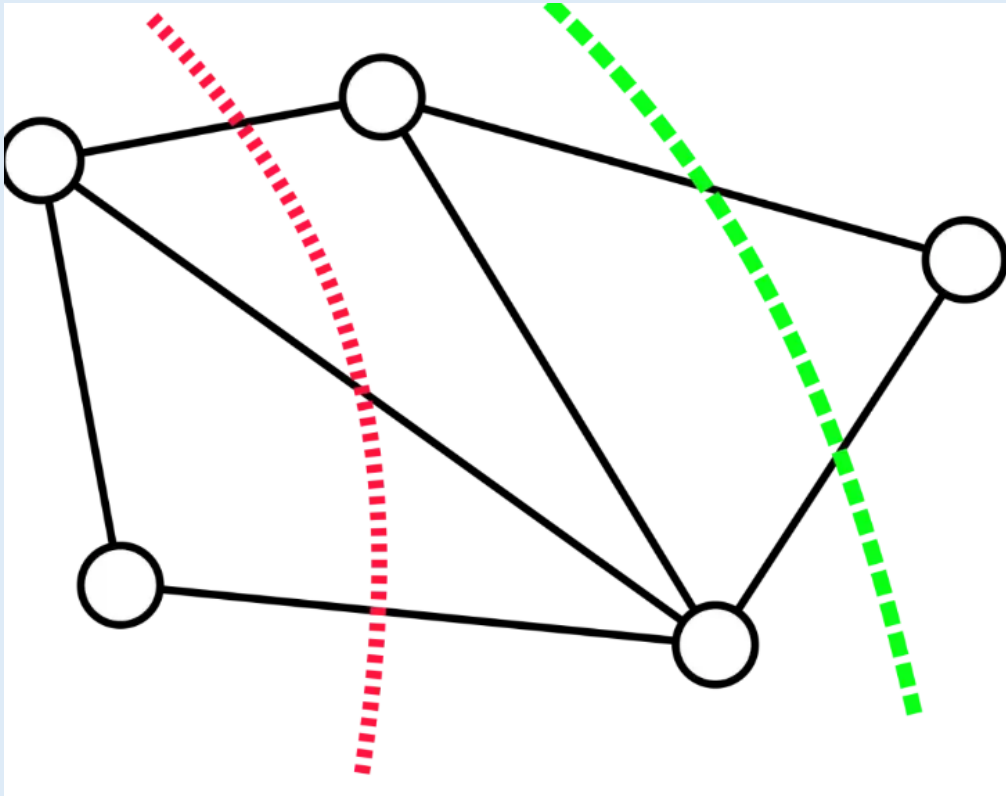
Edge cut set : $\{e_8\}, \{e_9\}, \{e_1, e_2\}, \{e_1, e_3, e_6\}, \{e_1, e_3, e_4, e_7\}$

■ Notes:

- (1) The **complete graph** K_n has no vertex cut set.
- (2) An **n -vertex null graph** has neither a vertex cut set nor an edge cut set.
- (3) If G is connected and E' is an edge cut set, then $p(G-E')=2$.
- (4) If G is connected and V' is a vertex cut set, then $p(G-V')\geq 2$.

6.2.2 Connectivity and Connectedness in Undirected

↳ The correct minimum cut problem



Deterministic Near-Linear Time Minimum Cut in Weighted Graphs

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Jason Li†

Satish Rao‡

Di Wang§

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Abstract

In 1996, Karger [Kar96] gave a startling randomized algorithm that finds a minimum-cut in a (weighted) graph in time $O(m \log^3 n)$ which he termed near-linear time meaning linear (in the size of the input) times a polylogarithmic factor. In this paper, we give the first deterministic algorithm which runs in near-linear time for weighted graphs.

Previously, the breakthrough results of Kawarabayashi and Thorup [KT19] gave a near-linear time algorithm for simple graphs (which was improved to have running time $O(m \log^2 n \log \log n)$ in [HRW20]). The main technique here is a clustering procedure that perfectly preserves minimum cuts. Recently, Li [Li21] gave an $m^{1+o(1)}$ deterministic minimum-cut algorithm for weighted graphs; this form of running time has been termed “almost-linear”. Li uses almost-linear time deterministic expander decompositions which do not perfectly preserve minimum cuts, but he can use these clusterings to, in a sense, “derandomize” the methods of Karger.

In terms of techniques, we provide a structural theorem that says there exists a sparse clustering that preserves minimum cuts in a weighted graph with $o(1)$ error. In addition, we construct it deterministically in near linear time. This was done exactly for simple graphs in [KT19, HRW20] and with polylogarithmic error for weighted graphs in [Li21]. Extending the techniques in [KT19, HRW20] to weighted graphs presents significant challenges, and moreover, the algorithm can only polylogarithmically approximately preserve minimum cuts. A remaining challenge is to reduce the polylogarithmic-approximate clusterings to $1+o(1/\log n)$ -approximate so that they can be applied recursively as in [Li21] over $O(\log n)$ many levels. This is an additional challenge that requires building on properties of tree-packings in the presence of a wide range of edge weights to, for example, find sources for local flow computations which identify minimum cuts that cross clusters.

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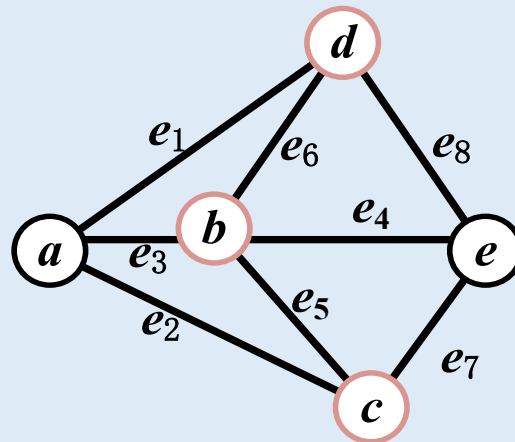
A graph and its *two cuts*: the red dashed lines indicate a cut consisting of three edges, while the green lines represent a *minimum cut of the graph*, consisting of two edges.

6.2.2 Connectivity and Connectedness in Undirected

↳ Vertex Connectivity and Edge Connectivity

- **Definition 6.10:** An undirected connected graph $G=\langle V,E\rangle$,
- $\kappa(G)=\min\{|V'| \mid V' \text{ is a vertex cut of } G \text{ or } G-V' \text{ becomes a trivial graph}\}$
is called the **vertex connectivity** of G .
 - $\lambda(G)=\min\{|E'| \mid E' \text{ is an edge cut of } G\}$
is called the **edge connectivity** of G .

■ **Example:**



$$\kappa(G)=3$$

$$\lambda(G)=3$$

6.2.2 Connectivity and Connectedness in Undirected

↳ The Connectivity Inequality in Undirected Graphs

■ Notes:

- (1) If G is a *trivial graph*, then $\kappa(G)=0$, $\lambda(G)=0$.
- (2) If G is a *complete graph* K_n , then $\kappa(G)=n-1$, $\lambda(G)=n-1$.
- (3) If G has a *cut vertex*, then $\kappa(G)=1$; if G has a *bridge* (cut edge), then $\lambda(G)=1$.
- (4) By convention, the vertex connectivity and edge connectivity of a *disconnected graph* are both defined to be 0.

■ Theorem 6.3: For *any undirected graph* G , we have

$$\kappa(G) \leq \lambda(G) \leq \delta(G).$$

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↳ Theorem on the Connectivity of Directed Graphs

- Let $D = \langle V, E \rangle$ be a directed graph, $u, v \in V$,
 - (1) u is **reachable** from v : There exists a path from u to v . By convention, every vertex is reachable from itself.
 - (2) u and v are **mutually reachable**: u is reachable from v , and v is reachable from u .
 - (3) D is **weakly connected** (connected): The undirected graph obtained by ignoring the directions of all edges is connected.
 - (4) D is **unilaterally connected**: $\forall u, v \in V$, either u is reachable from v or v is reachable from u .
 - (5) D is **strongly connected**: $\forall u, v \in V$, u and v are mutually reachable.
 - (6) D is **strongly connected** if and only if there **exists a circuit** that passes through all vertices.
 - (7) D is **unilaterally connected** if and only if there **exists a path** that passes through all vertices.

- **Shortest path** from u to v : The path from u to v with the minimum length (assuming u is reachable from v).
- **Distance $d\langle u, v \rangle$** : The length of the shortest path from u to v . If u is not reachable from v , then by convention, $\langle u, v \rangle = \infty$.
- Properties of a Distance Function $d\langle u, v \rangle$:
 - $d\langle u, v \rangle \geq 0$ and $d\langle u, v \rangle = 0 \iff u = v$
 - $d\langle u, v \rangle + d\langle v, w \rangle \geq d\langle u, w \rangle$
 - Note: Distance is *not symmetric*

6.2 Graph Connectivity • Brief summary

Objective :

Key Concepts :



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↳ 6.3 Matrix Representations of Graphs

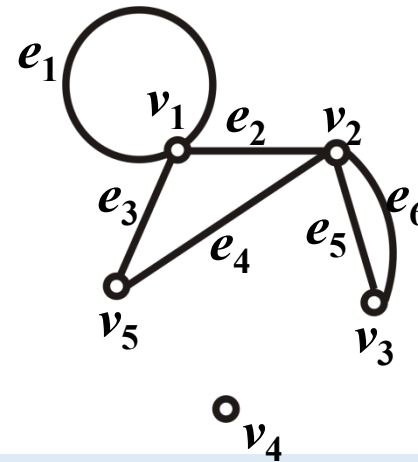
- 6.3.1 Incidence Matrix of an Undirected Graph
- 6.3.2 Incidence Matrix of a Directed Acyclic Graph
- 6.3.3 Adjacency Matrix of a Directed Graph, Adjacency Matrix of an Undirected Graph
The Number of Paths and Cycles in a Graph
- 6.3.4 Reachability Matrix of a Graph

↳ Definition of the Incidence Matrix

- Let $G = \langle V, E \rangle$, $V = \{v_1, v_2, \dots, v_n\}$, $E = \{e_1, e_2, \dots, e_m\}$.
 - Let m_{ij} be the incidence of vertex v_i with edge e_j , the matrix $(m_{ij})_{n \times m}$ is called the **incidence matrix** of G , denoted as **$M(G)$** . The possible values of m_{ij} : 0, 1, 2

Example:

$$M(G) = \begin{bmatrix} 2 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}$$



$$(1) \sum_{i=1}^n m_{ij} = 2, \quad j = 1, 2, \dots, m$$

$$(2) \sum_{j=1}^m m_{ij} = d(v_i), \quad i = 1, 2, \dots, n$$

$$(3) \sum_{i,j} m_{ij} = 2m$$

(4) e_j and e_k are *parallel edge*
 $\Leftrightarrow$ the j -th column and the k -th column are identical.

(5) V_i is an *isolated vertex* $\Leftrightarrow$ i -th row is all zeros.

(6) E_j is *loop* $\Leftrightarrow$ The first element in column j is 2, others are all 0.

↳ 6.3 Matrix Representations of Graphs

- 6.3.1 Incidence Matrix of an Undirected Graph
- 6.3.2 Incidence Matrix of a Directed Acyclic Graph
- 6.3.3 Adjacency Matrix of a Directed Graph, Adjacency Matrix of an Undirected Graph
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↳ The Incidence Matrix of a DAG

- Let the **directed acyclic graph** $D = \langle V, E \rangle$, $V = \{v_1, v_2, \dots, v_n\}$, $E = \{e_1, e_2, \dots, e_m\}$.

$$\text{Let } m_{ij} = \begin{cases} 1, & v_i \text{ is the starting point of } e_j \\ 0, & v_i \text{ is not incident to } e_j \\ -1, & v_i \text{ is the endpoint of } e_j \end{cases}$$

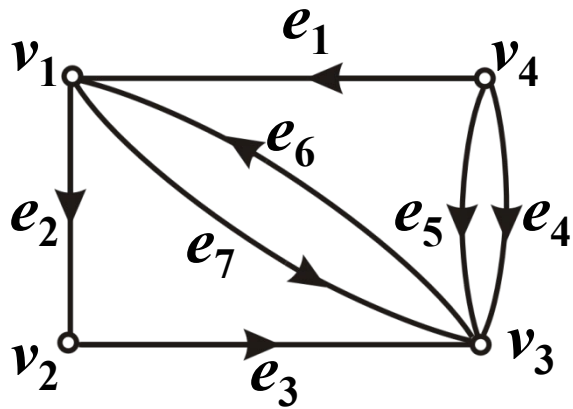
The matrix $(m_{ij})_{n \times m}$ called the incidence matrix of D , called $M(D)$.

■ Properties of a DAG:

- (1) Each column contains exactly one 1 and one -1.
- (2) The total number of 1's is equal to the total number of -1's, which equals the number of edges.
- (3) The number of 1's in the i -th row equals $d^+(v_i)$, and the number of -1's in the i -th row equals $d^-(v_i)$.
- (4) E_j and e_k are parallel edges $\Leftrightarrow$ the j -th column and the k -th column are identical.

6.3.2 Incidence Matrix of a Directed Acyclic Graph

↳ The Incidence Matrix of a DAG(e.g.)



$$M(D) = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & -1 & 1 \\ 0 & -1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & -1 & -1 & 1 & -1 \\ 1 & 0 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}$$

↳ 6.3 Matrix Representations of Graphs

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- **6.3.4 Reachability Matrix of a Graph**

↳ Adjacency Matrix of a Directed Graph

- Let $D=\langle V,E\rangle$, where $V=\{v_1, v_2, \dots, v_n\}$ and $E=\{e_1, e_2, \dots, e_m\}$,
Let the number of edges from vertex v_i to vertex v_j be denoted as $a_{ij}^{(1)}$. The matrix $(a_{ij}^{(1)})_{m \times n}$ is called the *adjacency matrix* of D , denoted as $A(D)$, or simply A .

- Properties of $A(D)$:

$$(1) \quad \sum_{j=1}^n a_{ij}^{(1)} = d^+(v_i), \quad i = 1, 2, \dots, n$$

The sum of the rows equals the outdegree of the graph.

$$(2) \quad \sum_{i=1}^n a_{ij}^{(1)} = d^-(v_j), \quad j = 1, 2, \dots, n$$

The sum of the columns equals the indegree of the graph.

Adjacency Matrix of a Directed Graph

Properties of $A(D)$:

$$(3) \sum_{i,j} a_{ij}^{(1)} = m$$

The sum of all the elements equals the number of edges.

$$(4) \sum_{i=1}^n a_{ii}^{(1)} = \text{the number of loops at } D$$

The sum of the diagonal elements equals the number of vertex loops.

Example:

